Analysis and Design of Algorithms Dynamic Programming

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Extremely powerful algorithmic technique with applications in optimization, scheduling, planning, economics, bioinformatics, etc.

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- **Extremely powerful algorithmic technique with** applications in optimization, scheduling, planning, economics, bioinformatics, etc
- \blacksquare At contests, probably the most popular type of problems
- \blacksquare A solution is usually not so easy to find, but when found, is easily implementable
- Need a lot of practice!

Fibonacci numbers

0, 1, 1, 2, 3, 5, 8, 13, 21, 34, . . .

Computing Fibonacci Numbers

Computing *Fⁿ*

Input: An integer $n \geq 0$.

Output: The *n*-th Fibonacci number *Fn*.

Computing Fibonacci Numbers

Computing *Fⁿ*

Input: An integer $n \geq 0$. Output: The *n*-th Fibonacci number *Fn*.

```
1
\mathcal{L}3
4
  def fib(n):
     i f n < = 1:
        return n
     return fib (n − 1) + fib (n − 2)
```
Recursion Tree

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- But Fibonacci numbers grow exponentially fast: $F_n \approx \varphi^n$, where $\varphi = 1.618...$ is the golden ratio
- **E.g.,** F_{150} **is already 31 decimal digits long**
- \blacksquare The Sun may die before your computer returns *F*150

Reason

Many computations are repeated

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"Those who cannot remember the past are condemned to repeat it." (George Santayana)

Reason

- Many computations are repeated
- *"Those who cannot remember the past are condemned to repeat it."* (George Santayana)
- A simple, but crucial idea: instead of recomputing the intermediate results, let's store them once they are computed

Memoization

```
1
2
3
4
 def fib(n):
  \textbf{if} \quad n \leq 1:
   return n
```
Memoization

```
def fib(n):
 if n \leq 1:
  return n

 T = \text{dict}()1
2
3
4
1
2
```

```
if n \leq 1:
         T[n] = ne lse :
          T[n] = f i b ( n − 1 ) + f i b ( n − 2 )
3 def fib(n):
4 if n not in T: 
5
6
7
8
```
10 **return** T[n]

9

But do we really need all this fancy stuff (recursion, memoization, dictionaries) to solve this simple problem?

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$$
\frac{1}{2} F_0 = 0, F_1 = 1
$$

$$
\frac{1}{2} F_2 = 0 + 1 = 1
$$

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- After all, this is how you would compute F_5 by hand:

$$
\begin{array}{ll}\n\mathbf{1} & F_0 = 0, F_1 = 1 \\
\mathbf{2} & F_2 = 0 + 1 = 1 \\
\mathbf{3} & F_3 = 1 + 1 = 2\n\end{array}
$$

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\mathbf{4} & F_4 = 1 + 2 = 3\n\end{array}
$$

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- After all, this is how you would compute F_5 by hand:

$$
F_0 = 0, F_1 = 1
$$

\n
$$
F_2 = 0 + 1 = 1
$$

\n
$$
F_3 = 1 + 1 = 2
$$

\n
$$
F_4 = 1 + 2 = 3
$$

\n
$$
F_5 = 2 + 3 = 5
$$

Iterative Algorithm

```
1
2
  def fib(n):
  T = [None] * (n + 1)3 \mid T[0], T[1] = 0, 14
5 for i in range ( 2 , n + 1 ) :
6 T [ i ] = T [ i − 1] + T [ i − 2]
7
8 return T[n]
```
Hm Again...

But do we really need to waste so much space?

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```
new current = previous + current
       previous, current = current, new current
1 def f i b ( n ) :
2 i f n <= 1 :
3 return n
4
5 previous, current = 0, 1
6 for _ in range ( n − 1 ) : 7
8
9
10 return current
```
O(*n*) additions

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■ On the other hand, recall that Fibonacci numbers grow exponentially fast: the binary length of *Fⁿ* is *O*(*n*)

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- In theory: we should not treat such additions as basic operations
- In practice: just F_{100} does not fit into a 64-bit integer type anymore, hence we need bignum arithmetic

Summary

The key idea of dynamic programming: **avoid recomputing the same thing again!**
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- \blacksquare The key idea of dynamic programming: avoid recomputing the same thing again!
- **At the same time, the case of Fibonacci** numbers is a slightly artificial example of dynamic programming since it is clear from the very beginning what intermediate results we need to compute the final result

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Longest Increasing Subsequence

Longest increasing

subsequence
Subsequence of the subsequence of Input: Output: An array $A = [a_0, a_1, \ldots, a_{n-1}].$ A longest increasing subsequence (LIS), i.e., a_{i_1} , a_{i_2} , \dots , a_{i_k} such that $i_1 < i_2 < \ldots < i_k$, $a_{i_1} < a_{i_2} < \cdots < a_{i_k}$, and *k* is maximal.

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- Moreover, the prefix of the IS ending at *z* must be an optimal IS ending at *z* as otherwise the initial IS would not be optimal:

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Optimal substructure by "cut-and-paste" trick

Let *LIS*(*i*) be the optimal length of a LIS ending \mathcal{L}_{max} at *A*[*i*]

Let *LIS(i)* be the optimal length of a LIS ending at *A*[*i*]

Then

LIS(*i*) = 1+max $\{LIS(j): j < i$ and $A[j] < A[i]\}$

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Convention: maximum of an empty set is equal to zero

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Then

LIS(*i*) = 1+max{*LIS*(*j*): $j < i$ and $A[j] < A[i]$ }

- **Convention:** maximum of an empty set is equal to zero
- Base case: $LS(0) = 1$

Algorithm

When we have a recurrence relation at hand, converting it to a recursive algorithm with memoization is just a technicality

We will use a table \overline{T} to store the results: $T[i] = LIS(i)$

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- We will use a table \overline{T} to store the results: *T* [*i*] = *LIS*(*i*)
- **Initially, T** is empty. When $LS(i)$ is computed, we store its value at *T* [*i*] (so that we will never recompute *LIS*(*i*) again)

Algorithm

When we have a recurrence relation at hand, converting it to a recursive algorithm with memoization is just a technicality

- We will use a table \overline{T} to store the results: *T* [*i*] = *LIS*(*i*)
- **Initially, T** is empty. When $LS(i)$ is computed, we store its value at *T* [*i*] (so that we will never recompute *LIS*(*i*) again)
- The exact data structure behind \overline{T} is not that important at this point: it could be an array or a hash table

Memoization

```
1 T = dict ()
 2
 3 def lis (A, i):
 4 i f i not in T :
 5 \tT[i] = 16
        7 for j in range ( i ) :
 8 i f A[ j ] < A[ i ] :
9 T[i] = max(T[i], lis(A, i) + 1)10
11 return T[i]
12
13 A = \begin{bmatrix} 7 & 2 & 1 & 3 & 8 & 4 & 9 & 1 & 2 & 6 & 5 & 9 & 3 \end{bmatrix}14 print (max( lis (A, i) for i in range (len (A) ) )
```
Running Time

The running time is quadratic (*O*(*n* 2)): there are *n* "serious" recursive calls (that are not just table lookups), each of them needs time *O*(*n*) (not counting the inner recursive calls)

Table and Recursion

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Table and Recursion

- \blacksquare We need to store in the table T the value of *LIS*(*i*) for all *i* from 0 to $n-1$
- Reasonable choice of a data structure for *T* : an array of size *n*
- **Moreover, one can fill in this array iteratively** instead of recursively

Iterative Algorithm

```
10
1
2
   def lis(A):
     T = [ None ] * len (A)
3
4 for i in range ( len (A ) ) :
5 T[i] = 1<br>
6 for i in6 for j in range ( i ) :
7 if A[i] < A[i] and T[i] < T[i] + 1:
8 T[i] = T[i] + 19
     relur max(T[i] for i in range (len(A)))
```
Iterative Algorithm

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def lis(A):
     T = [ None ] * len (A)
4 for i in range ( len (A ) ) :
5 T[i] = 1<br>
6 for i in6 for j in range ( i ) :
7 if A[i] < A[i] and T[i] < T[i] + 1:
8 T[i] = T[i] + 110 return max(T[i] for i in range(len(A)))
```
Crucial property: when computing *T* [*i*], *T* [*j*] for all *j* < *i* have already been computed

Iterative Algorithm

```
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   def lis(A):
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7 if A[i] < A[i] and T[i] < T[i] + 1:
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10 return max(T[i] for i in range(len(A)))
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- Crucial property: when computing *T* [*i*], *T* [*j*] for all *j* < *i* have already been computed
- Running time: *O*(*n* 2)

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Reconstructing a Solution

 \blacksquare How to reconstruct an optimal IS?

Reconstructing a Solution

- \blacksquare How to reconstruct an optimal IS?
- In order to reconstruct it, for each subproblem we will keep its optimal value and a choice leading to this value

Adjusting the Algorithm

```
prec = [None] * len(A)prev[i] = -1for j in range ( i ) :
           if A[i] < A[i] and T[i] < T[i] + 1:
             T[i] = T[i] + 11 def l i s (A ) :
 2 T = [ None ] * len (A) 
3
\frac{4}{5}5 for i in range ( len (A ) ) :
6 T[i] = 17
8
9
10
11 prev[i] = j
```
Unwinding Solution

```
last = 0for i in range ( 1 , len (A ) ) : 
  if T[i] > T[ last]:last = i\vert i s = \vert i
current = lastwhile current \ge 0:
  lis . append ( current )
  current = prev[current]lis.reverse()
return [A[i] for i in lis]
```


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- Subproblem: the length of an optimal increasing subsequence ending at *i*-th element
- A recurrence relation for subproblems can be immediately converted into a recursive algorithm with memoization
- A recursive algorithm, in turn, can be converted into an iterative one
- An optimal solution can be recovered either by using an additional bookkeeping info or by using the computed solutions to all subproblems

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- When a recurrence relation is written down, it can be wrapped with memoization to get a recursive algorithm
- In the previous section, we arrived at a reasonable subproblem by analyzing the structure of an optimal solution
- In this section, we'll provide an alternative way of arriving at subproblems: implement a naive brute force solution, then optimize it

Need the longest increasing subsequence? No $\mathcal{L}_{\mathcal{A}}$ problem! Just iterate over all subsequences and select the longest one:

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- Need the longest increasing subsequence? No problem! Just iterate over all subsequences and select the longest one:
	- Start with an empty sequence
	- Extend it element by element recursively
	- Keep track of the length of the sequence
- \blacksquare This is going to be slow, but not to worry: we will optimize it later

Brute Force: Code

```
11 for i in range(last_index + 1, len(A)):
13 result = max(result, lis (A, seq + [i])
 1 def l i s (A, seq ) :
2 result = len (seq)\frac{3}{4}if len (seq) = 0:
5 last index = -16 l ast _ e l ement = fl o a t ( "− i n f " )
7 e lse :
8 last index = seq [<sup>-1</sup>]
9 last element = A[ last index ]
10
12 if A[i] > last element:
14
15 return result
16
17 print ( lis (A = [7, 2, 1, 3, 8, 4, 9], seq = []))
```
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- \blacksquare For this, we pass the current sequence to each recursive call
- \blacksquare At the same time, code inspection reveals that we are not using all of the sequence: we are only interested in its last element and its length
- **Let's optimize!**

Optimized Code

```
result = seq len1 def lis (A, seq len, last index):
2 if last index = = −1:
3 l ast _ e l ement = fl o a t ( "− i n f " )
4 else :
5 last element = A[ last index ]
6
7
8
9 for i in range (last index + 1, len (A)):
10 if A[i] > last element:
11 result = max(result,
12 \vert \hspace{.1cm} \vert is (A, seq len + 1, i))
13
14 return result
15
16 print ( lis ( [3, 2, 7, 8, 9, 5, 8], 0, −1))
```
Inspecting the code further, we realize that seq len is not used for extending the current sequence (we don't need to know even the length of the initial part of the sequence to optimally extend it)

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- More formally, for any *x*, $extend(A, seq len, i)$ is equal to extend(A, seq len - x, i) + x
- \blacksquare Hence, can optimize the code as follows: $max(result, 1 + seq len + extend(A, 0, i))$

- Inspecting the code further, we realize that seq_len is not used for extending the current sequence (we don't need to know even the length of the initial part of the sequence to optimally extend it)
- More formally, for any *x*, $extend(A, seq len, i)$ is equal to extend(A, seq len - x, i) + x
- \blacksquare Hence, can optimize the code as follows: $max(result, 1 + seq len + extend(A, 0, i))$ **Excludes** seq len from the list of parameters!
Resulting Code

```
def lis (A, last index):
 1
 \overline{2}if last index == -1:
 \overline{3}last element = float('"=inf")\overline{\mathbf{4}}else:
 5<sup>5</sup>last element = A[last index]
 \boldsymbol{6}\overline{7}result = 08
9
       for i in range (last index + 1, len (A)):
         if A[i] > last element:
10<sup>°</sup>result = max(result, 1+ lis(A, i))
11
12
13
      return result
14
    print (lis ([8, 2, 3, 4, 5, 6, 7], -1))
15
```
Resulting Code

```
if A[i] > last element:
          result = max( result, 1 + lis (A, i))
1 def lis (A, last index):
2 if last index = = −1:
3 l ast _ e l ement = fl o a t ( "− i n f " )
4 e lse :
5 last element = A[ last index ]
6<br>7
     r esult = 08
9 for i in range (last index + 1, len(A)):
10
11
12
13 return result
14
15 p r i n t ( l i s ( [8 , 2 , 3 , 4 , 5 , 6 , 7] , −1))
```
It remains to add memoization!

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	- Analyze the structure of an optimal solution

- Subproblems (and recurrence relation on them) is the most important ingredient of a dynamic programming algorithm
- \blacksquare Two common ways of arriving at the right subproblem:
	- Analyze the structure of an optimal solution Implement a brute force solution and optimize it

Outline

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Statement

Edit distance

- Input: Two strings *A*[0 . . . *n −* 1] and *B*[0...*m*− 1].
- Output: The minimal number of insertions, deletions, and substitutions needed to transform *A* to *B*. This number is known as edit distance or Levenshtein distance.

EDITING

Example: $EDITING \rightarrow DISTANCE$

EDITING | remove E **DITING**

Example: $EDITING \rightarrow DISTANCE$

EDITING | remove E **DITING** | insert S **DISTING**

EDITING remove E DITING insert S DISTING replace I with by A DISTANG

EDITING remove E DITING insert S DISTING replace I with by A DISTANG replace G with C DISTANC

EDITING remove E DITING | insert S DISTING replace I with by A DISTANG replace G with C DISTANC insert E DISTANCE

Example: alignment

cost: 5

Example: alignment

substitutions/mismatches

$$
\frac{A[0 \ldots n-1]}{B[0 \ldots m-1]}
$$

Subproblems

Let $ED(i, j)$ be the edit distance of *A*[0 . . . *i −*1] and *B*[0. . . *j −*1].

Subproblems

- Let $ED(i, j)$ be the edit distance of *A*[0 . . . *i −*1] and *B*[0. . . *j −*1].
- We know for sure that the last column of an optimal alignment is either an insertion, a deletion, or a match/mismatch.

Subproblems

- Let *ED*(*i*, *i*) be the edit distance of *A*[0 . . . *i −*1] and *B*[0. . . *j −*1].
- We know for sure that the last column of an optimal alignment is either an insertion, a deletion, or a match/mismatch.
- What is left is an optimal alignment of the corresponding two prefixes (by cut-and-paste).

Recurrence Relation

$$
ED(i, j) = \min \begin{cases} ED(i, j-1) + 1 \\ ED(i-1, j) + 1 \\ ED(i-1, j-1) + diff(A[i], B[j]) \end{cases}
$$

Recurrence Relation

$$
ED(i, j) = \min \begin{cases} \n\end{cases}
$$

\n $ED(i, j - 1) + 1$
\n $ED(i - 1, j) + 1$
\n $ED(i - 1, j - 1) + diff(A[i], B[j])$

Base case: *ED*(*i*, 0) = *i*, *ED*(0, *j*) = *j*

Recursive Algorithm

```
1
 \overline{2}\overline{3}\overline{a}5
 6
 \overline{7}8
 9
10
11
12
13
14
15
16
17
18
```
 $T =$ dict ()

```
def edit distance (a, b, i, i):
  if not (i, i) in T:
    if i == 0: T[i, i] = ielif j == 0: T[i, j] = ielse:diff = 0 if a[i - 1] == b[j - 1] else 1
     T[i, i] = min(edit distance (a, b, i - 1, j) + 1,
        edit distance (a, b, i, j - 1) + 1,
          edit distance(a, b, i - 1, j - 1) + diff)
  return T[i, i]print (edit distance (a="editing", b="distance",
                     i = 7, i = 8)
```
Converting to a Recursive Algorithm

Use a 2D table to store the intermediate results

Converting to a Recursive Algorithm

- \blacksquare Use a 2D table to store the intermediate results
- *ED*(*i*, *j*) depends on *ED*(*i −*1, *j −*1), *ED*($i -1$, j), and *ED*(i , $j -1$):

Filling the Table

Fill in the table row by row or column by column:

Iterative Algorithm

```
diff = 0 if a[i − 1] == b[j − 1] else 1
         for i in range (1, \text{len}(a) + 1):
             for \bf{j} in range (1, \text{len}(b) + 1):
                T[i][i] = min(T[i - 1][i] + 1,T [ i ] [ j − 1] + 1 ,
                                           T [ i − 1 ][ j − 1] + d i f f )
         return T[ len (a) ] [ len (b) ]
 1 def edit distance (a, b):
 T = [[float("inf")] * (len(b) + 1)]<br>3 for in range (len(a) + 1)
                 for in range (len(a) + 1)
 4 fo r i in range ( len ( a ) + 1 ) :
 5 \overline{1} \overline{1} \overline{1} \overline{1} \overline{1} \overline{0} \overline{1} \overline{0} \overline{1} \overline{1} \overline{1} \overline{0} \overline{1} \overline{0} \overline{1} \overline{1} \overline{1} \overline{1} \overline{1} \overline{1} \overline{0} \overline{1} \overline{1} \overline{1} 6 fo r j i n range ( len ( b) + 1 ) :
            T[0][i] = i8
9
10
11
12
13
14
15
16
17
18
19 print (edit_d istance (a="distance", b="editing"))
```


Brute Force

Recursively construct an alignment column by column

Brute Force

- Recursively construct an alignment column by column
- Then note, that for extending the partially constructed alignment optimally, one only needs to know the already used length of prefix of *A* and the length of prefix of *B*

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 \blacksquare To reconstruct a solution, we go back from the cell (*n*, *m*) to the cell (0, 0)

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- If *ED*(*i*, *j*) = *ED*(*i −*1, *j*) + 1, then there exists an optimal alignment whose last column is a deletion

- \blacksquare To reconstruct a solution, we go back from the cell (*n*, *m*) to the cell (0, 0)
- If *ED*(*i*, *j*) = *ED*(*i −*1, *j*) + 1, then there exists an optimal alignment whose last column is a deletion
- If *ED*(*i*, *j*) = *ED*(*i*, *j −*1) + 1, then there exists an optimal alignment whose last column is an insertion

- \blacksquare To reconstruct a solution, we go back from the cell (*n*, *m*) to the cell (0, 0)
- If *ED*(*i* , *j*) = *ED*(*i −*1, *j*) + 1, then there exists an optimal alignment whose last column is a deletion
- If *ED*(*i* , *j*) = *ED*(*i* , *j −*1) + 1, then there exists an optimal alignment whose last column is an insertion
- If *ED*(*i* , *j*) = *ED*(*i −*1, *j −*1) + diff(*A*[*i*], *B* [*j*]), then match (if $A[i] = B[j]$) or mismatch (if $A[i] \neq B[i]$

EG

$$
\begin{array}{|c|c|c|c|}\n\hline\nT & A & N & C & E \\
\hline\nT & I & N & -G \\
\hline\n\end{array}
$$

$$
\begin{array}{|c|c|c|c|c|}\n\hline\nS & T & A & N & C & E \\
\hline\n- & T & I & N & - & G \\
\hline\n\end{array}
$$

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Saving Space

When filling in the matrix it is enough to keep $\overline{}$ only the current column and the previous column:

Saving Space

When filling in the matrix it is enough to keep only the current column and the previous column:

Thus, one can compute the edit distance of two given strings *A*[1 . . . *n*] and *B*[1. . . *m*] in time *O*(*nm*) and space *O*(min*{n*, *m}*).

However we need the whole table to find an actual alignment (we trace an alignment from the bottom right corner to the top left corner)

- However we need the whole table to find an actual alignment (we trace an alignment from the bottom right corner to the top left corner)
- \blacksquare There exists an algorithm constructing an optimal alignment in time *O*(*nm*) and space *O*(*n* + *m*) (Hirschberg's algorithm)

Weighted Edit Distance

- The cost of insertions, deletions, and substitutions is not necessarily identical
- \blacksquare Spell checking: some substitutions are more likely than others
- **Biology:** some mutations are more likely than others

Generalized Recurrence Relation

$$
\min \left\{\n \begin{aligned}\n &\text{ED}(i, j-1) + \text{inscost}(B[j]), \\
 &\text{ED}(i-1, j) + \text{delcost}(A[i]), \\
 &\text{ED}(i-1, j-1) + \text{substcost}(A[i], B[j])\n \end{aligned}\n \right.
$$

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Knapsack Problem

Goal

Maximize value (\$) while limiting total weight (kg)

Classical problem in combinatorial optimization with applications in resource allocation, cryptography, planning

- Classical problem in combinatorial optimization with applications in resource allocation, cryptography, planning
- Weights and values may mean various resources (to be maximized or limited):

- Classical problem in combinatorial optimization with applications in resource allocation, cryptography, planning
- **Neights and values may mean various resources** (to be maximized or limited):
	- \blacksquare Select a set of TV commercials (each commercial has duration and cost) so that the total revenue is maximal while the total length does not exceed the length of the available time slot

- Classical problem in combinatorial optimization with applications in resource allocation, cryptography, planning
- **Neights and values may mean various resources** (to be maximized or limited):
	- \blacksquare Select a set of TV commercials (each commercial has duration and cost) so that the total revenue is maximal while the total length does not exceed the length of the available time slot
	- **Purchase computers for a data center to achieve** the maximal performance under limited budget

knapsack

Problem Variations

Problem Variations

Knapsack with repetitions problem

- Input: *Weights w*₀, . . . , *w*_{*n*−1} and values *v*₀, . . . , *v*_{*n*−1} of *n* items; total weight *W* (*vi*'s, *wi*'s, and *W* are non-negative integers).
- Output: The maximum value of items whose weight does not exceed *W*. Each item can be used any number of times.

Analyzing an Optimal Solution

Consider an optimal solution and an item in it:

Analyzing an Optimal Solution

Consider an optimal solution and an item in it:

If we take this item out then we get an optimal solution for a knapsack of total weight *W −wi*.

Let *value*(*u*) be the maximum value of knapsack of weight *u*

Let *value*(*u*) be the maximum value of knapsack $\overline{}$ of weight *u*

> *value*(*u*) = max *{value*(*u −wi*) + *vi} i* : *wi≤w*

Let *value*(*u*) be the maximum value of knapsack $\overline{}$ of weight *u*

value(u) =
$$
\max_{i: w_i \leq w} \{ value(u - w_i) + v_i \}
$$

Base case: $value(0) = 0$

Let *value*(*u*) be the maximum value of knapsack $\overline{}$ of weight *u*

value(u) =
$$
\max_{i: w_i \leq w} \{ value(u - w_i) + v_i \}
$$

- Base case: $value(0) = 0$
- \blacksquare This recurrence relation is transformed into a recursive algorithm in a straightforward way

Recursive Algorithm

```
1 T = dict ()
 \frac{2}{3}6<br>7
11
13
14
```

```
def knapsack (w, v, u):
4 i f u not in T :
5 \quad T[u] = 07 for i in range ( len (w ) ) :
8 i f w[ i ] < = u :
9 T[u] = max(T[u],10 knapsack (w, v, u − w[i]) + v[i])
12 return T[u]
15 print (knapsack (w=[6, 3, 4, 2],
16 v = [30, 14, 16, 9], u = 10)
```
Recursive into Iterative

As usual, one can transform a recursive algorithm into an iterative one

Recursive into Iterative

- As usual, one can transform a recursive algorithm into an iterative one
- For this, we gradually fill in an array T : $T[u] = value(u)$

Recursive Algorithm

```
+ v [ i ])
7 T [ u ] = max(T[ u ] , T [ u − w[ i ] ] 
 1 def knapsack (W, w, v ) :
 2 T = \begin{bmatrix} 0 \end{bmatrix} * (W + 1)3
4 for u in range ( 1 , W + 1) :
5 for i in range ( len (w ) ) :
6 i f w[ i ] < = u :
8
      return T[W]
10
11
12 p r i n t ( knapsack (W=10 , w=[ 6 , 3 , 4 , 2] ,
13 v = [30, 14, 16, 9])
```
Example: $W = 10$

Example: $W = 10$

Example: $W = 10$

Subproblems Revisited

Another way of arriving at subproblems: optimizing brute force solution

Subproblems Revisited

- Another way of arriving at subproblems: optimizing brute force solution
- **Populate a list of used items one by one**

Brute Force: Knapsack with Repetitions

```
8 knapsack (W, w, v, items + [i])
1 def knapsack (W, w, v, items):
2 weight = sum(w[i] for i in items)3 value = sum(v[i] for i in items)
\frac{4}{5}5 for i in range ( len (w ) ) :
6 if weight + w[i] < w:
7 value = max(value,
9
10 return value
11
12 p r i n t ( knapsack (W=10 , w=[ 6 , 3 , 4 , 2] ,
13 v=[30, 14, 16, 9], items = []))
```
It remains to notice that the only important thing for extending the current set of items is the weight of this set

- It remains to notice that the only important thing for extending the current set of items is the weight of this set
- \blacksquare One then replaces items by their weight in the list of parameters

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With repetitions: unlimited quantities

Knapsack without repetitions problem

- Input: *Weights w*₀, . . . , *w*_{*n*−1} and values *v*₀, . . . , *v*_{*n*−1} of *n* items; total weight *W* (*vi*'s, *wi*'s, and *W* are non-negative integers).
- Output: The maximum value of items whose weight does not exceed *W*. Each item can be used at most once.

If the last item is taken into an optimal solution:

$$
W_{n-1} \qquad W
$$

then what is left is an optimal solution for a knapsack of total weight $W - w_{n-1}$ using items 0, 1, . . . , *n −*2.

If the last item is taken into an optimal solution:

$$
W_{n-1} \qquad W
$$

then what is left is an optimal solution for a knapsack of total weight *W −wn−*¹ using items 0, 1, . . . , *n −*2.

If the last item is not used, then the whole knapsack must be filled in optimally with items 0, 1, . . . , *n −*2.

For 0 *≤ u ≤ W* and 0 *≤ i ≤ n*, *value*(*u*, *i*) is the maximum value achievable using a knapsack of weight *u* and the first *i* items.
Subproblems

- For 0 *≤ u ≤ W* and 0 *≤ i ≤ n*, *value*(*u*, *i*) is the maximum value achievable using a knapsack of weight *u* and the first *i* items.
- Base case: $value(u, 0) = 0$, $value(0, i) = 0$

Subproblems

- For 0 *≤ u ≤ W* and 0 *≤ i ≤ n*, *value*(*u*, *i*) is the maximum value achievable using a knapsack of weight *u* and the first *i* items.
- Base case: $value(u, 0) = 0$, $value(0, i) = 0$ For *i* > 0, the item *i −*1 is either used or not: *value*(*u*, *i*) is equal to

max*{value*(*u−wi−*1, *i−*1)+*vi−*1, *value*(*u*, *i−*1)*}*

Recursive Algorithm

```
1 T = dict ()
\overline{2}3 def knapsack (w, v, u, i):
4 i f ( u , i ) not in T :
5 if i = 0:
6 T[u, i] = 07 e ls e :
8 T[ u, i ] = knapsack (w, v, u, i − 1)
9 i f u > = w[ i − 1 ]:
10 T[u, i] = max(T[u, i],11 knapsack (w, v , u − w[ i − 1] , i − 1) + v [ i — 1 ]
12
13 return T[ u, i]
14
15
16 p ri n t ( knapsack ( w = [ 6 , 3 , 4 , 2 ] ,
17 v = [30, 14, 16, 9], u = 10, i = 4)
```
Iterative Algorithm

```
2 T = [[None] * (len (w) + 1) for _ in range (W + 1)]
     for u in range (W + 1):
       T[u][0] = 0for i in range (1, \text{len}(w) + 1):
        for u in range (W + 1):
          T [ u ] [ i ] = T [ u ] [ i − 1]
          if u > = w[i - 1]:
            T[u][i] = max(T[u][i],T [ u − w[ i − 1 ] ] [ i − 1] + v [ i − 1 ])
     r eturn T[W] [ len (w) ]
1 def knapsack (W, w, v ) :
3
4
5
6
7
8
9
10
11
12
13
14
15
16
17 p ri n t ( knapsack (W=10 , w=[ 6 , 3 , 4 , 2 ] ,
18 v = [ 30, 14, 16, 9])
```
Analysis

Running time: *O*(*nW*)

Analysis

Running time: *O*(*nW*) ■ Space: $O(nW)$

Analysis

- Running time: $O(nW)$
- Space: $O(nW)$
- Space can be improved to $O(W)$ in the iterative version: instead of storing the whole table, store the current column and the previous one

 \blacksquare As it usually happens, an optimal solution can be unwound by analyzing the computed solutions to subproblems

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- Start with $u = W$, $i = n$

- \blacksquare As it usually happens, an optimal solution can be unwound by analyzing the computed solutions to subproblems
- Start with $u = W$, $i = n$
- If *value*(*u*, *i*) = *value*(*u*, *i −*1), then item *i −*1 is not taken. Update *i* to *i −*1

 \blacksquare As it usually happens, an optimal solution can be unwound by analyzing the computed solutions to subproblems

Start with $u = W$, $i = n$

- If *value*(*u*, *i*) = *value*(*u*, *i −*1), then item *i −*1 is not taken. Update *i* to *i −*1
- **Otherwise**

value(*u*, *i*) = *value*($u - w_{i-1}$, $i - 1$) + v_{i-1} and the item *i − i* is taken. Update *i* to *i −* 1 and *u* to *u −wi−*¹

Subproblems Revisited

How to implement a brute force solution for the $\mathcal{L}_{\mathcal{A}}$ knapsack without repetitions problem?

Subproblems Revisited

- How to implement a brute force solution for the knapsack without repetitions problem?
- **Process items one by one. For each item, either** take into a bag or not

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Recursive vs Iterative

If all subproblems must be solved then an iterative algorithm is usually faster since it has no recursion overhead

Recursive vs Iterative

- \blacksquare If all subproblems must be solved then an iterative algorithm is usually faster since it has no recursion overhead
- \blacksquare There are cases however when one does not need to solve all subproblems and the knapsack problem is a good example: assume that *W* and all *wi*'s are multiples of 100; then *value*(*w*) is not needed if *w* is not divisible by 100

The running time *O*(*nW*) is not polynomial $\mathcal{L}_{\mathcal{A}}$ since the input size is proportional to log *W*, but not *W*

- The running time *O*(*nW*) is not polynomial since the input size is proportional to log *W*, but not *W*
- In other words, the running time is $O(n2^{\log W})$.

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 \blacksquare E.g., for

W = 10 345 970 345 617 824 751

(twentу digits only!) the algorithm needs roughly 10²⁰ basic operations

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- In other words, the running time is $O(n2^{\log W})$.

 \blacksquare E.g., for

W = 10 345 970 345 617 824 751

(twentу digits only!) the algorithm needs roughly 10²⁰ basic operations

Solving the knapsack problem in truly polynomial time is the essence of the P vs NP problem, the most important open problem in Computer Science (with a bounty of \$1M)

Fractional Knapsack

The time complexity of the Fractional Knapsack problem is O(N log N).

This complexity arises because the problem is typically solved using a **greedy algorithm**, which involves sorting the items based on their value-toweight ratio and then adding them to the knapsack in this sorted order until the knapsack's capacity is reached or all items are considered

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Chain matrix multiplication

Input: Chain of *n* matrices A_0 , ..., A_{n-1} to be multiplied.

Output: An order of multiplication minimizing the total cost of multiplication.

■ Denote the sizes of matrices A_0, \ldots, A_{n-1} by

$m_0 \times m_1, m_1 \times m_2, \ldots, m_{n-1} \times m_n$

respectively. I.e., the size of A_i is $m_i \times m_{i+1}$

Denote the sizes of matrices *A*0, . . . , *An−*¹ by

 $m_0 \times m_1$, $m_1 \times m_2$, ..., $m_{n-1} \times m_n$

respectively. I.e., the size of A_i is $m_i \times m_{i+1}$ Matrix multiplication is not commutative (in general, $A \times B \neq B \times A$), but it is associative: $A \times (B \times C) = (A \times B) \times C$

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*m*⁰ *× m*1, *m*¹ *× m*2, . . . , *mn−*1*× mⁿ*

respectively. I.e., the size of A_i is $m_i \times m_{i+1}$

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- **Fig. 1.1.** Thus $A \times B \times C \times D$ can be computed, e.g., as $(A \times B) \times (C \times D)$ or $(A \times (B \times C)) \times D$

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- **Matrix multiplication is not commutative (in** general, $A \times B \neq B \times A$), but it is associative: $A \times (B \times C) = (A \times B) \times C$
- **Thus** $A \times B \times C \times D$ **can be computed, e.g., as** $(A \times B) \times (C \times D)$ or $(A \times (B \times C)) \times D$
- \blacksquare The cost of multiplying two matrices of size *p × q* and *q × r* is *pqr*

Example: $A \times c \cdot (B \times C) \times D$

cost:

cost: 20 *·* 1 *·* 10

 $cost: 20 \cdot 1 \cdot 10 + 20 \cdot 10 \cdot 100$

Example: $A \times c \cdot (B \times C) \times D$

A × B × C × D 50×100

cost: $20 \cdot 1 \cdot 10 + 20 \cdot 10 \cdot 100 + 50 \cdot 20 \cdot 100 = 120200$

cost:

cost: 50 *·* 20 *·* 1

$\cot: 50 \cdot 20 \cdot 1 + 1 \cdot 10 \cdot 100$

A × B × C × D 50×100

cost: $50 \cdot 20 \cdot 1 + 1 \cdot 10 \cdot 100 + 50 \cdot 1 \cdot 100 = 7000$
Order as a Full Binary Tree

 $((A \times B) \times C) \times$ *D*

 $A \times ((B \times C) \times D)$

 $(A \times (B \times C)) \times D$

Analyzing an Optimal Tree

each subtree computes the product of A_p , ..., A_q for some $p \leq q$

Subproblems

Let $M(i, j)$ be the minimum cost of computing $A_i \times \cdots \times A_{i-1}$

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 \blacksquare Then

$$
M(i, j) = \min \{M(i, k) + M(k, j) + m_i \cdot m_k \cdot m_j\}
$$

$$
m_k \cdot m_j\}
$$

Subproblems

- Let $M(i, j)$ be the minimum cost of computing $A_i \times \cdots \times A_{i-1}$ **■** Then
	- $M(i, j) = min \{M(i, k) + M(k, j) + m_i \cdot m_k\}$ *· mj} i<k<j*

Base case: $M(i, i + 1) = 0$

Recursive Algorithm

 $\mathbf{1}$ $\overline{2}$ $\overline{3}$ $\overline{4}$ 5 66 $\overline{7}$ 8 $\overline{9}$ 10 11 12 13 14 15 16 17

 $T = \text{dict}()$

```
def matrix mult(m, i, j):
  if (i, j) not in T:
  if i = i + 1:
    TI i i = 0else:
     T[i, i] = float("inf")for k in range(i + 1, j):
       T[i, j] = min(T[i, j],matrix mult(m, i, k) +
          matrix mult(m, k, i) +
         m[i] * m[i] * m[k])return T[i, i]print (matrix mult (m=[50, 20, 1, 10, 100], i=0, j=4))
```
Converting to an Iterative Algorithm

- We want to solve subproblems going from smaller size subproblems to larger size ones
- The size is the number of matrices needed to be multiplied: *j −i*
- A possible order:

Example

The matrices have size 4 x 10, 10 x 3, 3 x 12, 12 x 20, 20 x 7

Example

The matrices have size 4 x 10, 10 x 3, 3 x 12, 12 x 20, 20 x 7

M [2, 4] = min $\begin{cases} M[2,3] + M[4,4] + p_1p_3p_4 = 360 + 0 + 10.12.20 = 2760 \\ M[2,2] + M[3,4] + p_1p_2p_4 = 0 + 720 + 10.3.20 = 1320 \end{cases}$ M [3, 5] = 1140

Iterative Algorithm

```
def matrix mult(m):
 \mathbf{1}\overline{2}n = len(m) - 1\begin{array}{c} 3 \\ 4 \\ 5 \end{array}T = [[float("inf"]] * (n + 1) for in range(n + 1)]for i in range(n):
 \overline{6}T[i][i + 1] = 0\begin{array}{c} 7 \\ 8 \end{array}for s in range(2, n + 1):
 \overline{9}for i in range(n - s + 1):
10
            i = i + s11
             for k in range(i + 1, j):
               T[i][i] = min(T[i][i],12
13
                 T[i][k] + T[k][i] +m[i] * m[i] * m[k])14
15
16
       return T[0][n]17
18
    print(matrix \text{ mult}(m=[50, 20, 1, 10, 100]))
```
Final Remarks

Running time: *O*(*n* 3)

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- To unwind a solution, go from the cell (0, *n*) to a cell (*i* , *i* + 1)
- **Brute force search: recursively enumerate all** possible trees

Outline

1: Longest Increasing [Subsequence](#page-1-0)

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Step 1 (the most important step)

Define subproblems and write down a recurrence relation (with a base case) \blacksquare either by analyzing the structure of an optimal solution, or by optimizing a brute force

solution

Subproblems: Review

- ¹ Longest increasing subsequence: *LIS* (*i*) is the length of longest common subsequence ending at element *A*[*i*]
- **2** Edit distance: $ED(i, j)$ is the edit distance between prefixes of length *i* and *j*
- **3** Knapsack: $K(w)$ is the optimal value of a knapsack of total weight *w*
- **4** Chain matrix multiplication $M(i, j)$ is the optimal cost of multiplying matrices through *i* to *j −*1

Convert a recurrence relation into a recursive algorithm:

- store a solution to each subproblem in a table
- before solving a subproblem check whether its solution is already stored in the table

Convert a recursive algorithm into an iterative algorithm:

- **n** initialize the table
- go from smaller subproblems to larger ones
- **specify an order of subproblems**

Prove an upper bound on the running time. Usually the product of the number of subproblems and the time needed to solve a subproblem is a reasonable estimate.

Uncover a solution

Exploit the regular structure of the table to check whether space can be saved

Recursive vs Iterative

■ Advantages of iterative approach:

- No recursion overhead
- **May allow saving space by exploiting a regular** structure of the table
- Advantages of recursive approach:
	- May be faster if not all the subproblems need to be solved
	- An order on subproblems is implicit